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an adaptive lane keeping controller was proposed in [15] In order to deal with the vehicle dynamics uncertainty and Modeling and Nonlinear Adaptive Control for Autonomous Vehicle

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9. MODELING NONLINEAR SYSTEMS: THE CLASSICAL APPROACH 9.1 Introduction to the chapter It should be obvious from the chapter on the classical approach to nonlinear

## **9. The input used and the identification process should be**

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### **Adaptive Nonlinear Stabilization Control for a Quadrotor**

Nonlinear Adaptive Robust Control Theory and Applications Bin Yao School of Mechanical Engineering Purdue University West Lafayette, IN47907

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